

Fig. 1

[illegible]

P2

S2/P1

15

Fig. 2A

	S ₂
	S ₁
	MR

P1 —
P2

Fig. 2B

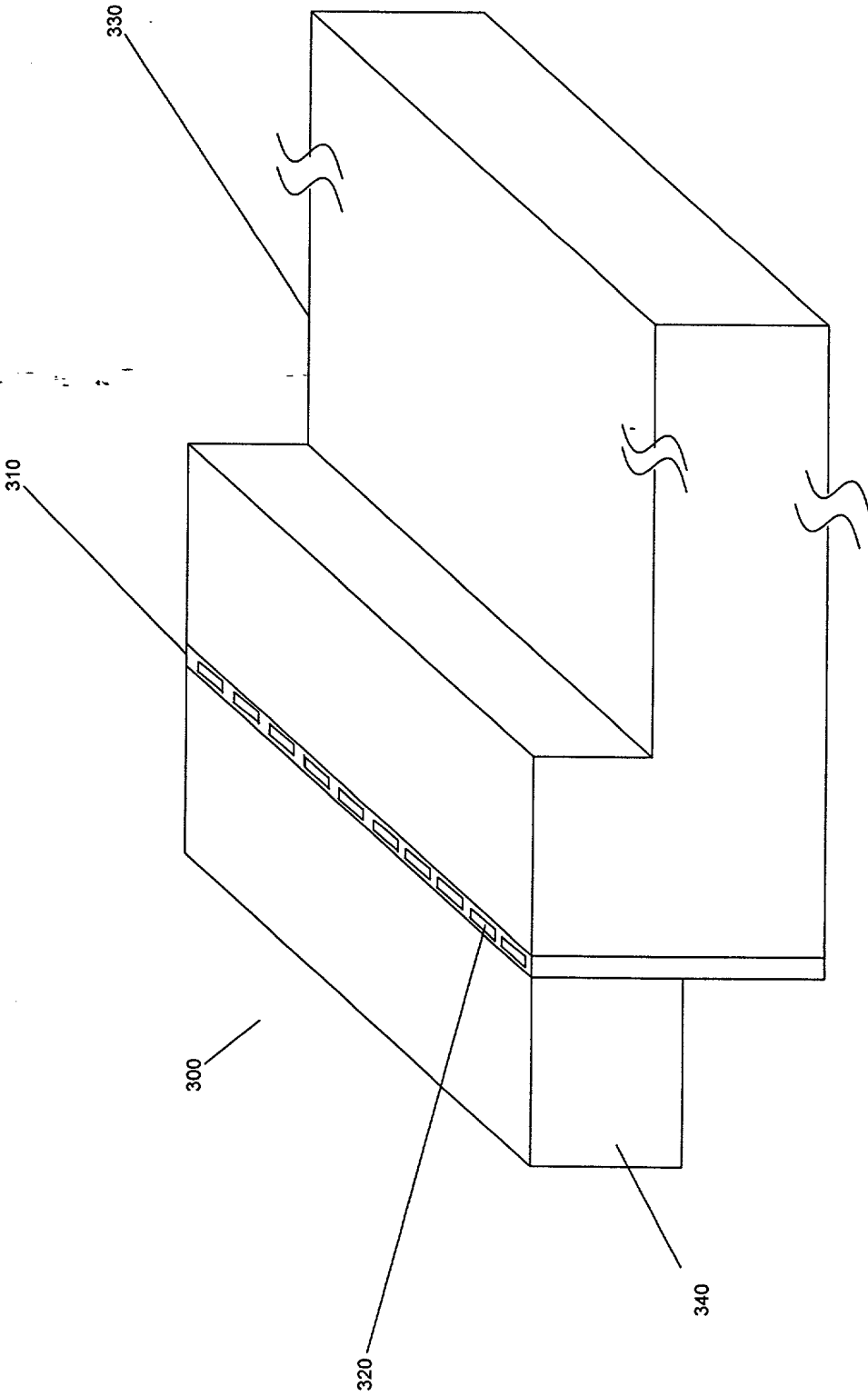


Fig. 3

FIG. 4 is a perspective view of the device 100 in a folded state, showing the first portion 110 and the second portion 120. The device 100 is shown in a folded state, with the first portion 110 and the second portion 120. The device 100 is shown in a folded state, with the first portion 110 and the second portion 120.

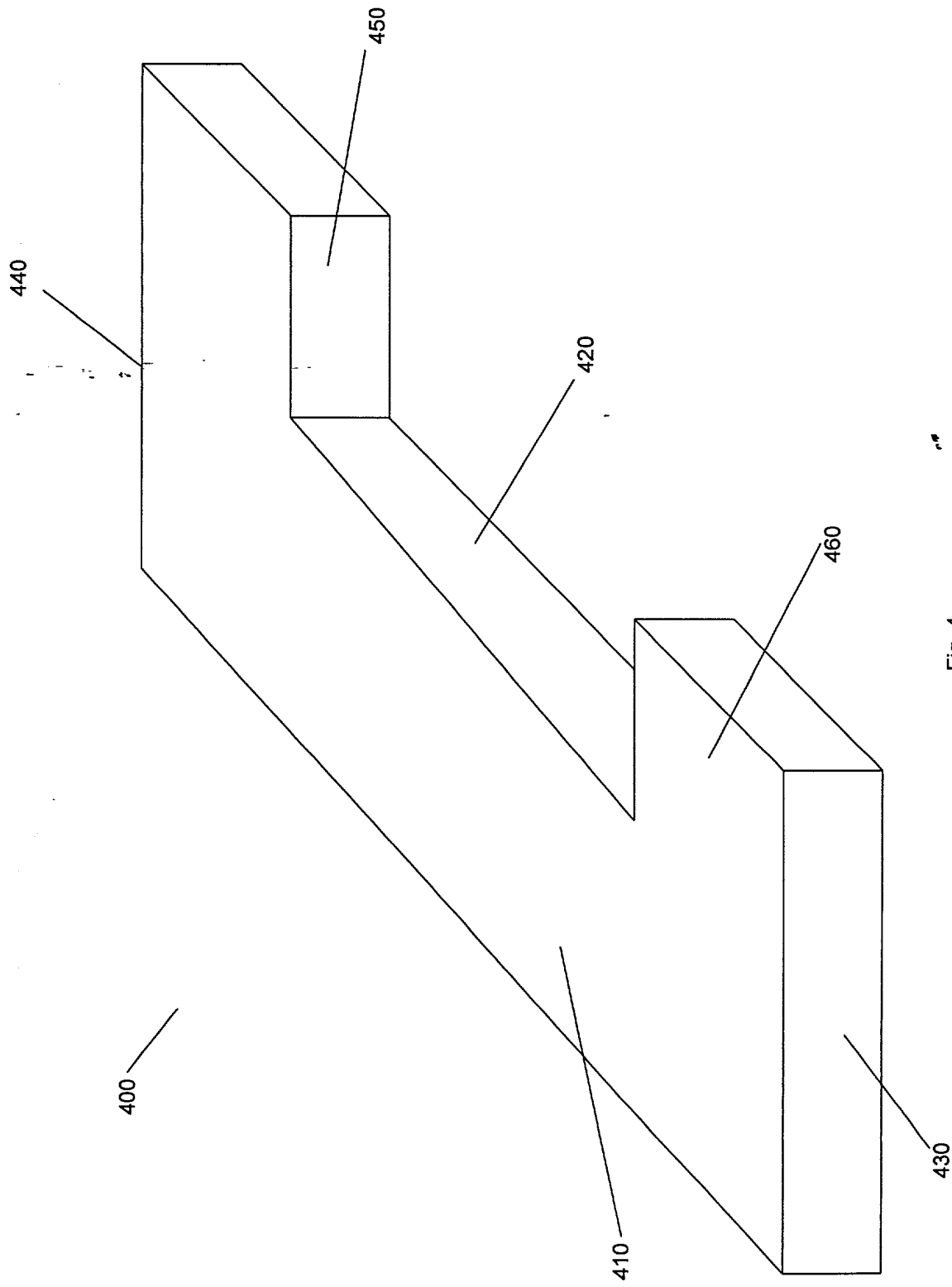


Fig. 4

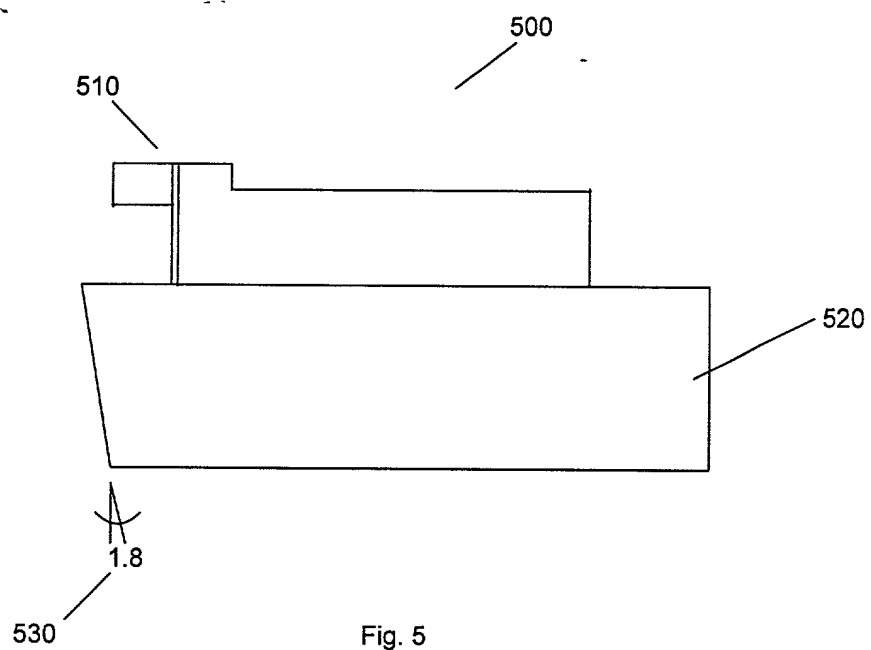


Fig. 5

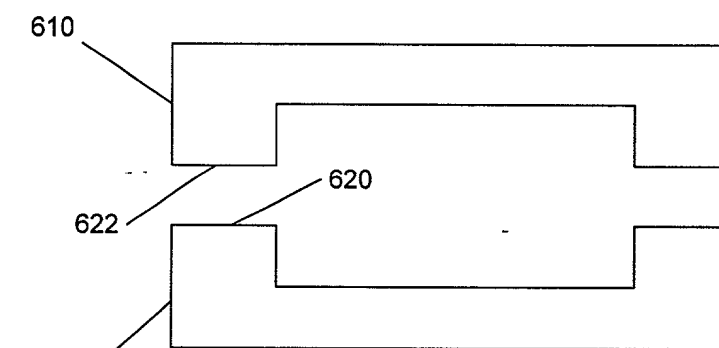


Fig. 6A

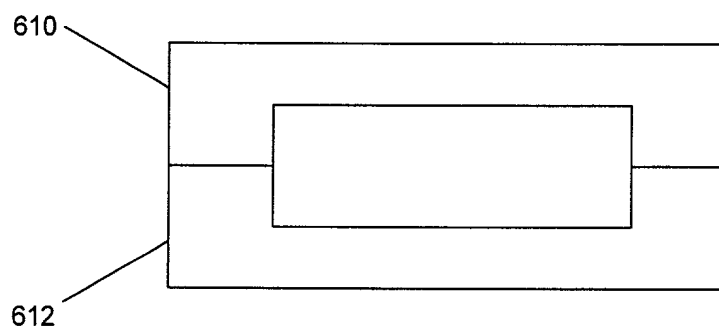


Fig. 6B

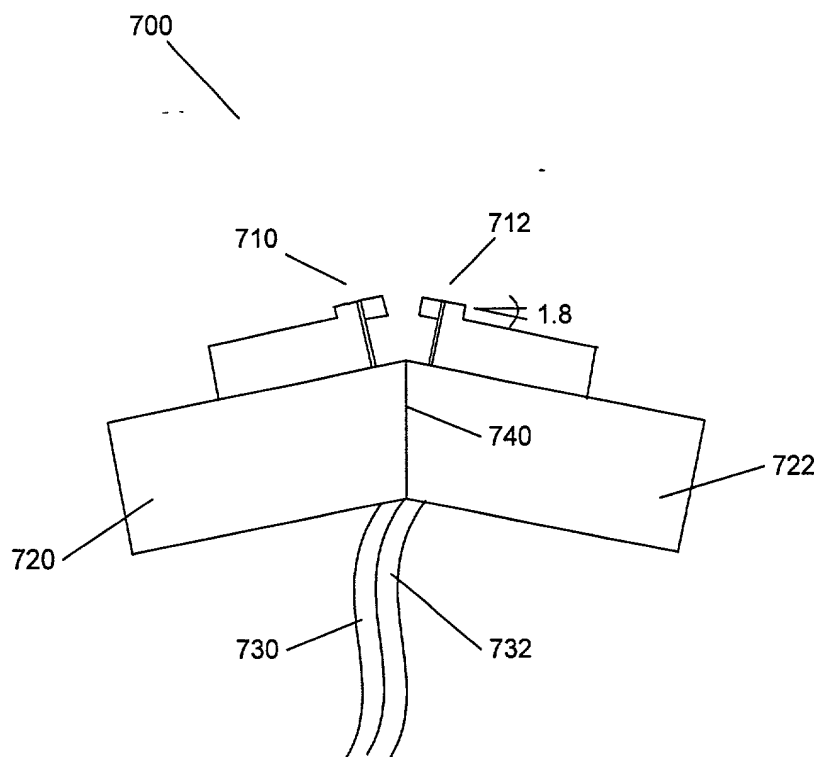


Fig. 7

800

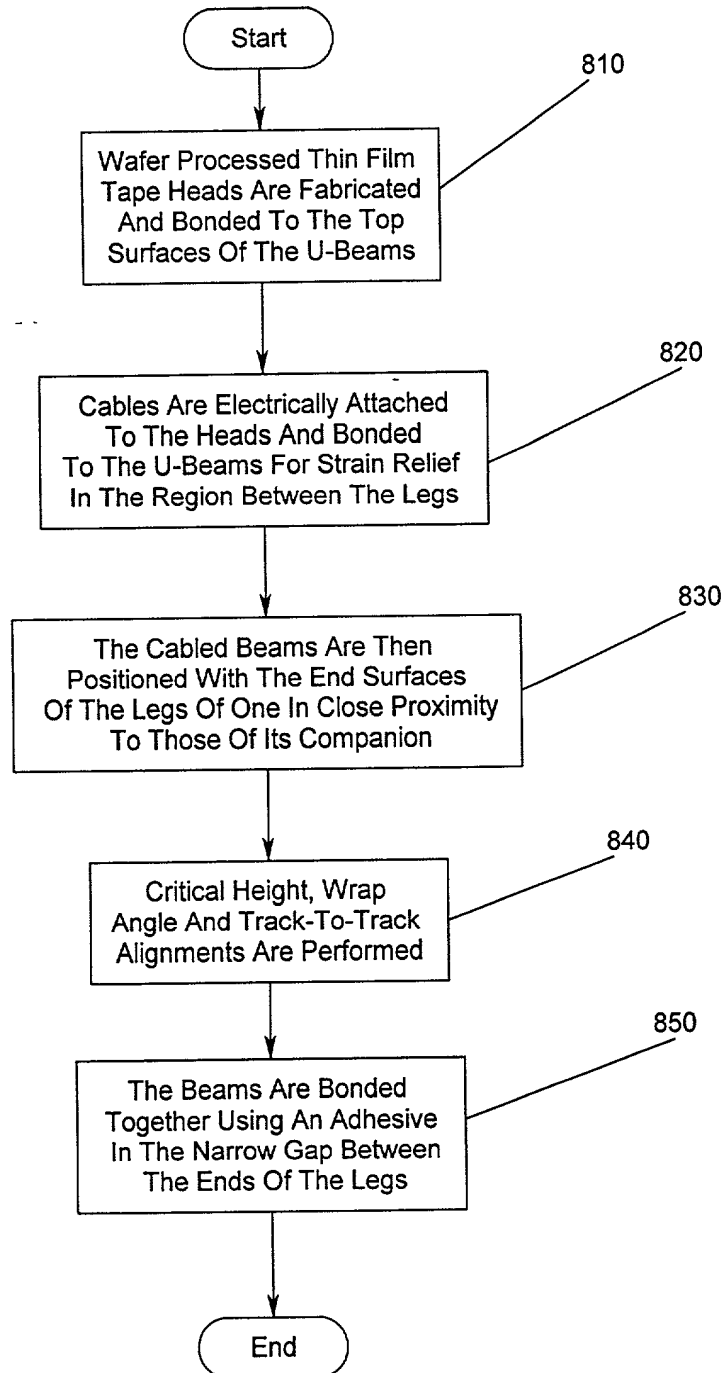


Fig. 8

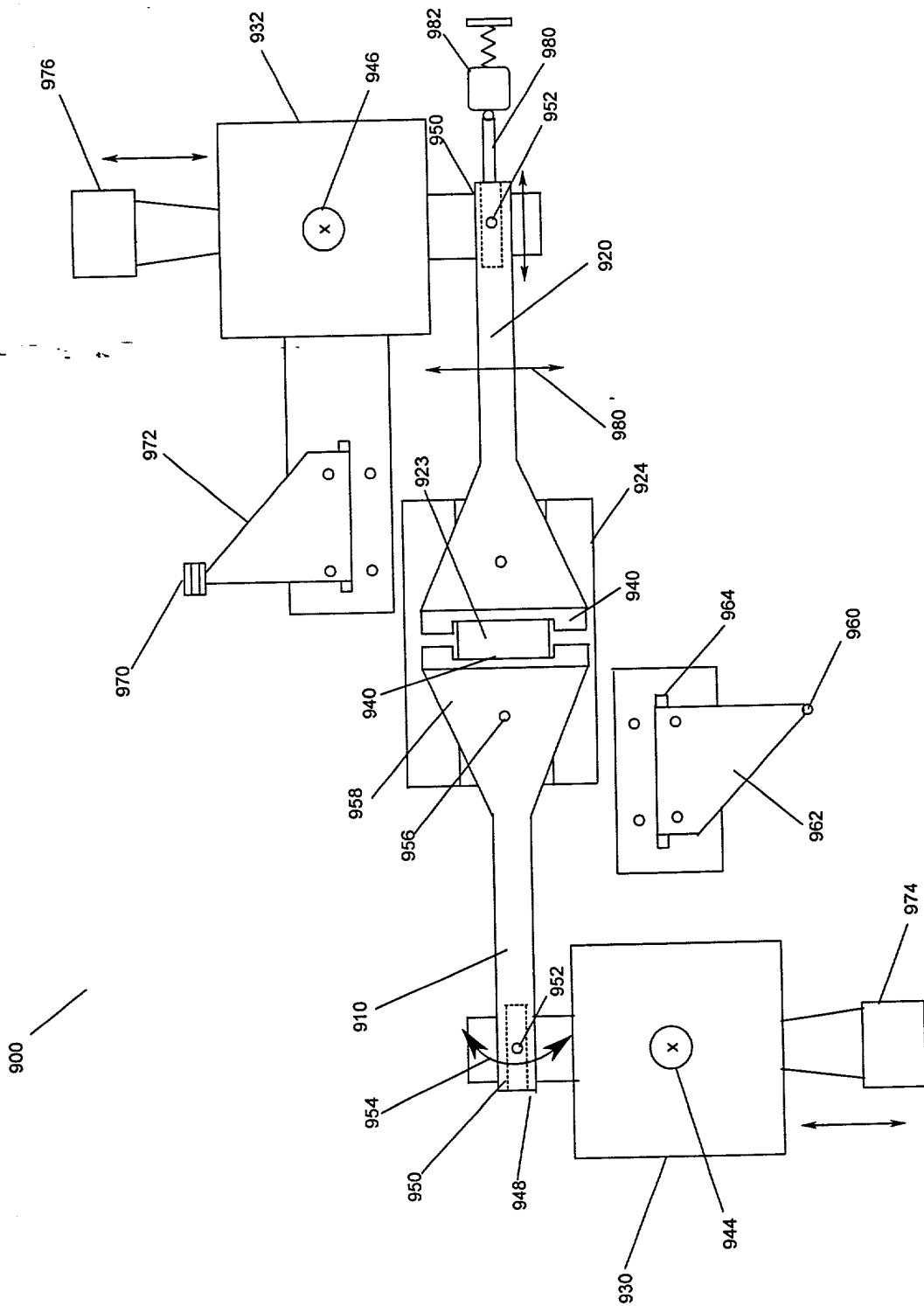


Fig. 9

FIG. 10a is a perspective view of a first embodiment of a device 1000. The device 1000 includes a base 1002, a first arm 1010, a second arm 1014, a first joint 1016, a second joint 1018, a first end effector 1050, a second end effector 1056, a first handle 1090, and a second handle 1090. The first arm 1010 is connected to the base 1002 at the first joint 1016. The second arm 1014 is connected to the base 1002 at the second joint 1018. The first end effector 1050 is connected to the first arm 1010 at the first joint 1016. The second end effector 1056 is connected to the second arm 1014 at the second joint 1018. The first handle 1090 is connected to the first arm 1010 at the first joint 1016. The second handle 1090 is connected to the second arm 1014 at the second joint 1018.

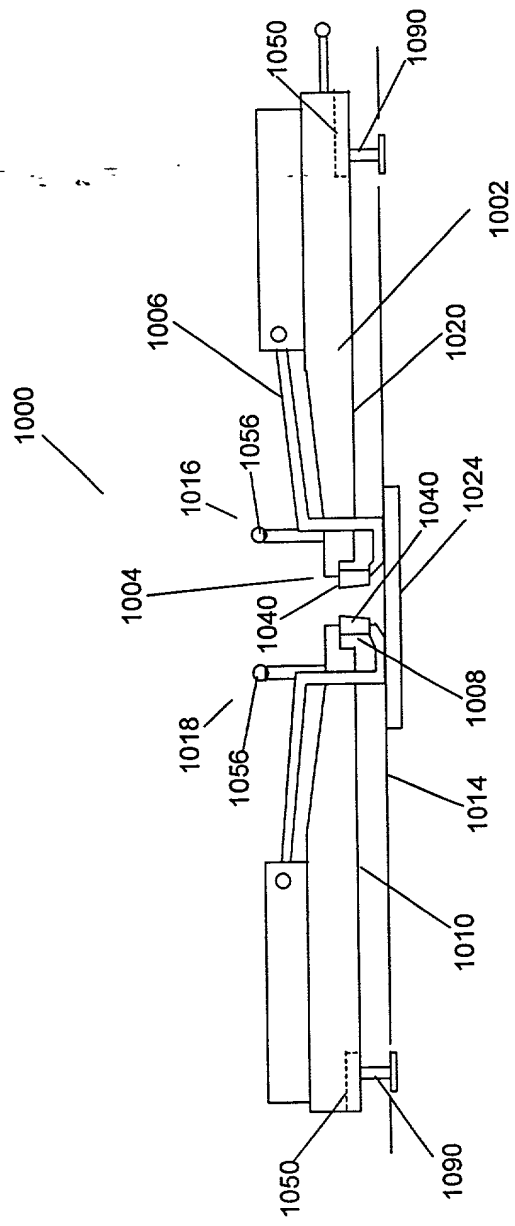


Fig. 10a

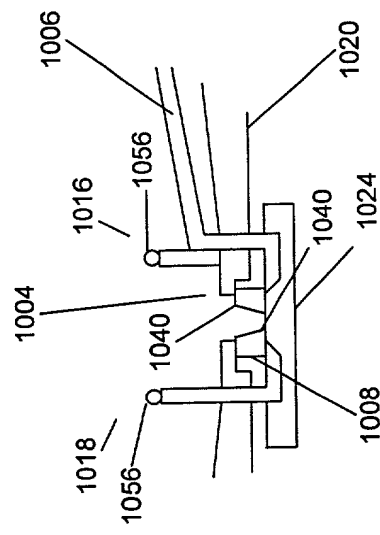


Fig. 10b

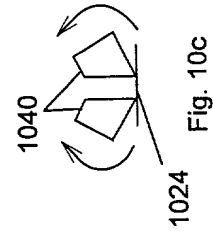


Fig. 10c

1100

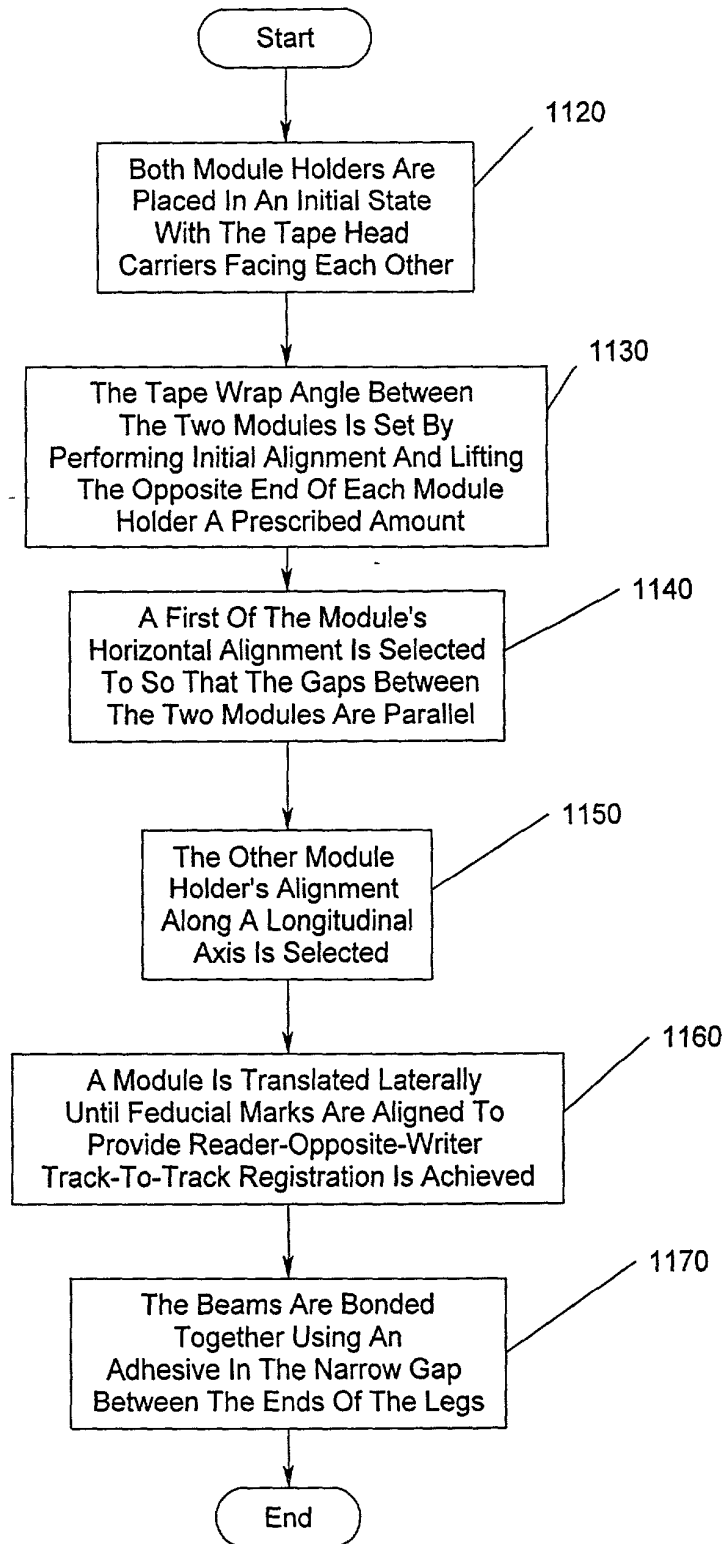


Fig. 11

1200

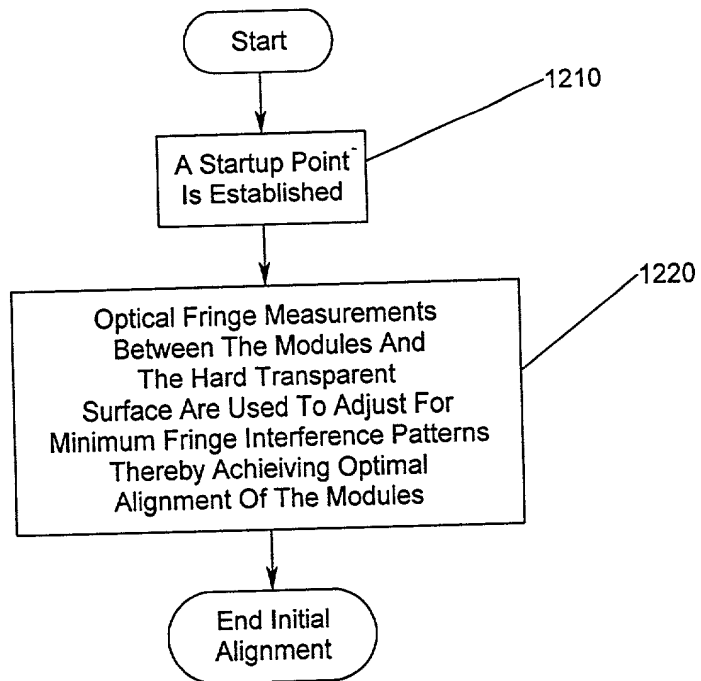


Fig. 12